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Wireless Robotics

This science experiment was chosen because it was thought to be a good skill to learn, and an interesting one as well. The purpose of this experiment was to create a robot that had been pre-programmed to do what the operator commands the robot to do. This paper talks about wireless robotics and the means of transmission and operation. In conclusion I can say that the newly redone robot can be easily controlled by wireless through a pair of 434 MHz transmitter and receiver. The transmitter and receiver can distinguish one another and clearly transmit and receive data packages. We are confident that the robot is easier to control now that it has the new components wired up.